



Unbounded Solutions to Systems of Differential Equations at Resonance

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Dedicated to the memory of Russell Johnson

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Abstract

We deal with a weakly coupled system of ODEs of the type

$$x_j'' + n_j^2 x_j + h_j(x_1, \dots, x_d) = p_j(t), \quad j = 1, \dots, d,$$

with h_j locally Lipschitz continuous and bounded, p_j continuous and 2π -periodic, $n_j \in \mathbb{N}$ (so that the system is at resonance). By means of a Lyapunov function approach for discrete dynamical systems, we prove the existence of unbounded solutions, when either global or asymptotic conditions on the coupling terms h_1, \dots, h_d are assumed.

Keywords Systems of ODEs · Unbounded solutions · Resonance · Lyapunov function

Mathematics Subject Classification 34C11 · 34C15

1 Introduction

In this paper, we deal with the existence of unbounded solutions for weakly coupled systems of ODEs of the type

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$$\begin{cases} x_1'' + n_1^2 x_1 + h_1(x_1, \dots, x_d) = p_1(t), \\ x_2'' + n_2^2 x_2 + h_2(x_1, \dots, x_d) = p_2(t), \\ \vdots \\ x_d'' + n_d^2 x_d + h_d(x_1, \dots, x_d) = p_d(t), \end{cases} \quad (1.1)$$

where the functions $h_1, \dots, h_d : \mathbb{R}^d \rightarrow \mathbb{R}$ are locally Lipschitz continuous and bounded and the functions $p_1, \dots, p_d : \mathbb{R} \rightarrow \mathbb{R}$ are continuous and periodic with the same period, say 2π for simplicity. We will also assume that

$$n_j \in \mathbb{N} \quad \text{for every } j \in \{1, \dots, d\}, \quad (1.2)$$

implying, as well-known, that the scalar equation $x_j'' + n_j^2 x_j = 0$ has a nontrivial 2π -periodic solution (in fact, all its nontrivial solutions are 2π -periodic). Following a popular terminology (cf. [21]), system (1.1) is thus said to be at resonance.

In the scalar case (that is, $d = 1$), the problem of the existence of unbounded solutions has been considered since the nineties. Indeed, the first result can be essentially traced back to Seifert [22], establishing the existence of unbounded solutions to the equation

$$x'' + n^2 x + h(x) = p(t), \quad x \in \mathbb{R}, \quad (1.3)$$

as a consequence of a non-existence result for 2π -periodic solutions by Lazer and Leach [17] together with the classical Massera's theorem. Later on, sharper conclusions were obtained by Alonso and Ortega in [1]. In particular, according to [1, Proposition 3.1], any solution of (1.3) is unbounded both in the past and in the future whenever

$$2(\sup h - \inf h) \leq \left| \int_0^{2\pi} p(t)e^{int} dt \right|; \quad (1.4)$$

moreover, due to [1, Proposition 3.4], any sufficiently large solution is unbounded either in the past or in the future when the global condition (1.4) is replaced by the (weaker) asymptotic assumption

$$2 \left| \max \left\{ \limsup_{x \rightarrow +\infty} h(x), \limsup_{x \rightarrow -\infty} h(x) \right\} - \min \left\{ \liminf_{x \rightarrow +\infty} h(x), \liminf_{x \rightarrow -\infty} h(x) \right\} \right| < \left| \int_0^{2\pi} p(t)e^{int} dt \right|.$$

Both results were proved via an abstract method, based on the use of Lyapunov-like functions, developed in the same paper. Generalizations of this kind of results to more general situations (like asymmetric oscillators and planar Hamiltonian systems) were then obtained by many authors (see, among others, [2,6–10,16,18,20,21,23] and the references therein).

Yet, as far as we know, the boundedness problem for system (1.1) is rather unexplored. The aim of the present paper is to provide some results in this direction, by investigating to what extent the method developed in [1] could be successfully applied to systems of second order equations.

Roughly speaking, we will show in Sect. 2 that a first result, Theorem 2.1, can be easily achieved when appropriate global conditions are imposed on the coupling terms h_1, \dots, h_d . In such a situation, the resonance assumption (1.2) can be even weakened into

$$n_j \in \mathbb{N} \quad \text{for some } j \in \{1, \dots, d\}.$$

Moreover, with the same approach, it is possible to consider a genuinely vectorial problem like

$$x'' + Ax + h(x) = p(t), \quad x \in \mathbb{R}^d,$$

where $h : \mathbb{R}^d \rightarrow \mathbb{R}^d$, $p : \mathbb{R} \rightarrow \mathbb{R}^d$ and A is a symmetric, positive definite, $d \times d$ matrix which has n^2 as eigenvalue, with $n \in \mathbb{N}$ (see Theorem 2.3).

The possibility of obtaining results with asymptotic assumptions on the functions h_1, \dots, h_d is then studied in Sect. 3. As expected, this is a much more delicate issue, since the coupling between the equations plays an essential role. It seems then necessary to focus the attention on quite specific choices for the coupling terms h_1, \dots, h_d ; we will investigate in details the case of the cyclic coupling

$$h_j(x_1, \dots, x_d) = h_j(x_{j+1}) \tag{1.5}$$

and of the radial coupling

$$h_j(x_1, \dots, x_d) = h_j\left(\sqrt{x_1^2 + \dots + x_d^2}\right). \tag{1.6}$$

We refer to Theorems 3.1 and 3.2 for the precise statements; notice that some care must be taken to describe the sets of solutions which are unbounded.

Let us finally recall that, for scalar second order equations at resonance, the existence of unbounded solutions is strictly related to the existence of periodic solutions, and these problems are often considered together. In this regard, we mention that, despite some recent results obtained about periodic solutions for weakly coupled systems of ODEs (see, for instance, [5,13–15,19] and the references therein), the existence of periodic solutions for systems like (1.1) under the resonance assumption (1.2) seems to be a quite open issue (we are just aware of [3]).

Notation. Throughout the paper, the symbol $|\cdot|$ will be freely used to denote the absolute value of a real number, the modulus of a complex number or the Euclidean norm of a k -dimensional vector for $k \leq d$ (the specific meaning will be clear from the context). We also denote $\mathbb{N} = \{1, 2, 3, \dots\}$.

2 A Global Result

In this section we prove the existence of unbounded solutions for system (1.1) under global assumptions on the coupling terms h_1, \dots, h_d . For brevity, from now on we write (1.1) in compact form as

$$x_j'' + n_j^2 x_j + h_j(x) = p_j(t), \quad j = 1, \dots, d, \tag{2.1}$$

where $x = (x_1, \dots, x_d)$, and we assume $n_j > 0$, $h_j : \mathbb{R}^d \rightarrow \mathbb{R}$ locally Lipschitz continuous and bounded and $p_j : \mathbb{R} \rightarrow \mathbb{R}$ continuous and 2π -periodic (for every j). Our result reads as follows.

Theorem 2.1 *In the previous setting, assume that*

$$n_j \in \mathbb{N} \quad \text{and} \quad 2(\sup h_j - \inf h_j) < \left| \int_0^{2\pi} p_j(t)e^{in_j t} dt \right| \quad \text{for some } j \in \{1, \dots, d\}. \tag{2.2}$$

Then, for every solution x of (2.1) it holds that

$$\lim_{|t| \rightarrow +\infty} (x_j(t)^2 + x'_j(t)^2) = +\infty.$$

Let us observe that this result is, basically, of scalar nature: indeed, assumption (2.2) involves only the j -th equation of system (2.1) and, accordingly, the conclusion is for the j -th component of the vector solution (x_1, \dots, x_d) . Of course, in the case when system (2.1) is fully at resonance (meaning that (1.2) is satisfied), and the global assumption $2(\sup h_j - \inf h_j) < \left| \int_0^{2\pi} p_j(t)e^{in_j t} dt \right|$ holds for every $j = 1, \dots, d$, then it follows that all the components of any solution of (2.1) are unbounded, both in the past and in the future.

Remark 2.2 We recall the following fact (cf. [1, Lemma 3.2]) which will be used several times throughout the paper: for every integrable function q and every $n \in \mathbb{N}$, it holds that

$$\left| \int_0^{2\pi} q(t)e^{int} dt \right| = \max_{\varphi \in [0, 2\pi]} \int_0^{2\pi} q(t) \sin(nt + \varphi) dt.$$

We are now in a position to give the proof of Theorem 2.1.

Proof Let x be a solution of (2.1). We divide the proof in two steps.

Step 1. Let $k \in \mathbb{Z}$; we show that

$$\lim_{|k| \rightarrow +\infty} (x_j(2k\pi)^2 + x'_j(2k\pi)^2) = +\infty. \tag{2.3}$$

To this end, according to Remark 2.2, let $\varphi_j \in [0, 2\pi]$ be such that

$$\left| \int_0^{2\pi} p_j(t)e^{in_j t} dt \right| = \int_0^{2\pi} p_j(t) \sin(n_j t + \varphi_j) dt \tag{2.4}$$

and let

$$\Gamma = \int_0^{2\pi} p_j(t) \sin(n_j t + \varphi_j) dt - 2(\sup h_j - \inf h_j). \tag{2.5}$$

In view of assumption (2.2), it results $\Gamma > 0$.

Let us now define the Lyapunov-like function

$$V(\zeta, \eta) = \eta \sin \varphi_j - n_j \zeta \cos \varphi_j, \quad \forall (\zeta, \eta) \in \mathbb{R}^2. \tag{2.6}$$

A simple computation shows that for every integer $k > 0$ we have

$$\begin{aligned}
 &V(x_j(2k\pi), x'_j(2k\pi)) - V(x_j(0), x'_j(0)) \\
 &= \left[x'_j(t) \sin(n_j t + \phi_j) \right]_0^{2k\pi} - n_j \left[x_j(t) \cos(n_j t + \phi_j) \right]_0^{2k\pi} \\
 &= \int_0^{2k\pi} \left[x''_j(t) + n_j^2 x_j(t) \right] \sin(n_j t + \phi_j) dt \\
 &= \int_0^{2k\pi} p_j(t) \sin(n_j t + \phi_j) dt - \int_0^{2k\pi} h_j(x(t)) \sin(n_j t + \phi_j) dt \\
 &\geq k \int_0^{2\pi} p_j(t) \sin(n_j t + \phi_j) dt - \sup h_j \int_0^{2k\pi} \sin^+(n_j t + \phi_j) dt \\
 &\quad + \inf h_j \int_0^{2k\pi} \sin^-(n_j t + \phi_j) dt \\
 &= k \int_0^{2\pi} p_j(t) \sin(n_j t + \phi_j) dt - 2k(\sup h_j - \inf h_j),
 \end{aligned}$$

where $\sin^+ s = \max\{\sin s, 0\}$ and $\sin^- s = \max\{-\sin s, 0\}$. Recalling (2.5), we then deduce that

$$V(x_j(2k\pi), x'_j(2k\pi)) - V(x_j(0), x'_j(0)) \geq k\Gamma, \quad \forall k \in \mathbb{N}.$$

This implies that

$$\lim_{k \rightarrow +\infty} V(x_j(2k\pi), x'_j(2k\pi)) = +\infty,$$

thus proving (2.3) when $k \rightarrow +\infty$.

When k is a negative integer, by arguing as above it is possible to prove that

$$V(x_j(0), x'_j(0)) - V(x_j(2k\pi), x'_j(2k\pi)) \geq -k\Gamma,$$

implying that

$$\lim_{k \rightarrow -\infty} V(x_j(2k\pi), x'_j(2k\pi)) = -\infty.$$

and finally (2.3) when $k \rightarrow -\infty$.

Step 2. We prove that

$$\lim_{|t| \rightarrow +\infty} \left(x_j(t)^2 + x'_j(t)^2 \right) = +\infty. \tag{2.7}$$

To this end, let

$$M_j = \sup |h_j| + \sup |p_j|$$

and define the partial energy function

$$E_j(t) = \frac{1}{2} x'_j(t)^2 + \frac{1}{2} n_j^2 x_j(t)^2 + \frac{1}{2} M_j^2, \quad \forall t \in \mathbb{R}.$$

A simple computation shows that

$$E'_j(t) = [p_j(t) - h_j(x_1(t), \dots, x_d(t))] x'_j(t), \quad \forall t \in \mathbb{R},$$

and thus, using the elementary inequality $|ab| \leq \frac{1}{2}(a^2 + b^2)$ for $a, b \in \mathbb{R}$,

$$|E'_j(t)| \leq E_j(t), \quad \forall t \in \mathbb{R}.$$

Gronwall's Lemma then yields

$$E_j(t) \geq e^{2k\pi-t} E_j(2k\pi) \geq e^{-2\pi} E_j(2k\pi), \quad \forall t \in [2k\pi, 2(k+1)\pi), \tag{2.8}$$

where k is the integer part of $t/2\pi$. Taking into account (2.3) and the definition of E_j , from (2.8) we deduce that

$$\lim_{t \rightarrow +\infty} E_j(t) = +\infty,$$

which implies (2.7) when $t \rightarrow +\infty$. The proof for $t \rightarrow -\infty$ is analogous. □

In the remaining part of this section, we show how to deal, using the same scheme of proof, with the more general system

$$x'' + Ax + h(x) = p(t), \quad x \in \mathbb{R}^d, \tag{2.9}$$

where A is a $d \times d$ matrix, $h : \mathbb{R}^d \rightarrow \mathbb{R}^d$ is locally Lipschitz continuous and bounded, $p : \mathbb{R} \rightarrow \mathbb{R}^d$ is continuous and 2π -periodic (of course, system (2.1) enters this setting, with A diagonal). Before stating the result, we recall that the linear homogeneous system

$$x'' + Ax = 0, \tag{2.10}$$

has a nontrivial 2π -periodic solution if and only if A has an eigenvalue of the form n^2 , for some $n \in \mathbb{N}$. With this in mind, the following result holds true (in the statement, $\langle \cdot, \cdot \rangle$ stands for the Euclidean scalar product in \mathbb{R}^d and $|\cdot|$ for the associated norm).

Theorem 2.3 *In the previous setting, suppose that the matrix A is symmetric and positive definite and assume that there exists $n \in \mathbb{N}$ such that n^2 is an eigenvalue of A . Finally, suppose that there exists a nontrivial 2π -periodic solution v of (2.10) satisfying*

$$\sup |h| \int_0^{2\pi} |v(t)| dt < \left| \int_0^{2\pi} \langle p(t), v(t) \rangle dt \right|. \tag{2.11}$$

Then, for every solution x of (2.9) it holds that

$$\lim_{|t| \rightarrow +\infty} (|x(t)|^2 + |x'(t)|^2) = +\infty. \tag{2.12}$$

Proof Let x be a solution of (2.9). We first observe that it is sufficient to prove that

$$\lim_{|k| \rightarrow +\infty} (|x(2k\pi)|^2 + |x'(2k\pi)|^2) = +\infty, \tag{2.13}$$

where k is an integer. Indeed, defining the energy function

$$E(t) = \frac{1}{2}|x'(t)|^2 + \frac{1}{2}\langle Ax(t), x(t) \rangle + \frac{1}{2}M^2, \quad \forall t \in \mathbb{R},$$

where $M = \sup(|p| + |h|)$, by arguing as in the second step of the proof of Theorem (2.1) it can be shown that (2.13) implies (2.12) (here, we use the fact that A is positive definite).

We now show the validity of (2.13) when $k \rightarrow +\infty$; the case of $k \rightarrow -\infty$ is similar. Assume then $k > 0$ and let

$$\Gamma' = \left| \int_0^{2\pi} \langle p(t), v(t) \rangle dt \right| - \sup |h| \int_0^{2\pi} |v(t)| dt; \tag{2.14}$$

observe that $\Gamma' > 0$ by (2.11). Let us define

$$V(\zeta, \eta) = \langle \eta, v(0) \rangle - \langle \zeta, v'(0) \rangle, \quad \forall (\zeta, \eta) \in \mathbb{R}^d \times \mathbb{R}^d.$$

As in the previous proof, a standard computation shows that

$$\begin{aligned} V(x(2k\pi), x'(2k\pi)) - V(x(0), x'(0)) &= \int_0^{2k\pi} \langle x''(t) + Ax(t), v(t) \rangle dt \\ &= \int_0^{2k\pi} \langle p(t), v(t) \rangle dt - \int_0^{2k\pi} \langle h(x(t)), v(t) \rangle dt \\ &\geq k \int_0^{2\pi} \langle p(t), v(t) \rangle dt - \sup |h| \int_0^{2k\pi} |v(t)| dt \\ &= k \int_0^{2\pi} \langle p(t), v(t) \rangle dt - k \sup |h| \int_0^{2\pi} |v(t)| dt. \end{aligned}$$

Recalling (2.14), we then deduce that

$$V(x(2k\pi), x'(2k\pi)) - V(x(0), x'(0)) \geq k\Gamma', \quad \forall k \in \mathbb{N}.$$

This implies that

$$\lim_{k \rightarrow +\infty} V(x(2k\pi), x'(2k\pi)) = +\infty,$$

thus proving (2.13) when $k \rightarrow +\infty$. □

It is worth noticing that, with the same proof, Theorem 2.3 could be extended to the case of an infinite-dimensional system like

$$x'' + Ax + h(x) = p(t), \quad x \in \mathcal{H},$$

where \mathcal{H} is a real Hilbert space and $A : \mathcal{H} \rightarrow \mathcal{H}$ is a positive, bounded and self-adjoint linear operator. In fact, Alonso and Ortega in [1, Section 4] already considered the case of a semilinear wave equation at resonance. For some recent advances on the topic of ODEs in Hilbert spaces, see [4,11,12] and the references therein.

We end this section with a comparison between Theorems 2.1 and 2.3 in the case when A is a diagonal matrix.

Remark 2.4 Theorem 2.3 is of vectorial nature. In the case of a diagonal matrix A , when compared with Theorem (2.1) it requires a stronger condition in the coupling term h . Indeed, if n_j^2 is the eigenvalue of A corresponding to an integer n_j , we can take

$$v(t) = \sin(n_j t + \varphi_j) e_j, \quad \forall t \in \mathbb{R},$$

where φ_j is as in (2.4) and e_j is the j -th vector of the standard basis of \mathbb{R}^d : hence, assumption (2.11) reads as

$$\int_0^{2\pi} p_j(t) \sin(n_j t + \varphi_j) dt = \left| \int_0^{2\pi} p_j(t) e^{in_j t} dt \right| > \sup |h| \int_0^{2\pi} |\sin(n_j t + \varphi_j)| dt = 4 \sup |h|,$$

which is stronger than (2.2) since

$$4 \sup |h| \geq 4 \sup |h_j| \geq 2(\sup h_j - \inf h_j).$$

On the other hand, a sharper result in the general case of system (2.9) can be proved by diagonalizing the matrix A . Indeed, let Q be an orthogonal matrix such that $QAQ^T = D$ is diagonal and let $y = Qx$. The original system (2.9) is then transformed in

$$y'' + Dy + h^*(y) = p^*(t), \tag{2.15}$$

where $h^*(y) = Qh(Q^T y)$ and $p^*(t) = Qp(t)$. As a consequence, an unboundedness result for x can be obtained by applying Theorems (2.1) to (2.15) when

$$2(\sup h_j^* - \inf h_j^*) < \left| \int_0^{2\pi} p_j^*(t)e^{in_j t} dt \right|.$$

This is a sharper assumption compared to (2.11), but it involves the matrix Q , whose knowledge is not required in (2.11).

3 Two Asymptotic Results

In this section, we deal again with system (2.1), by studying a couple of situations in which the assumptions on the nonlinear coupling term involve its asymptotic behavior rather than the span of its image. Whenever $n_j \in \mathbb{N}$, we will use again (cf. (2.6)) the Lyapunov function $V_{j,\varphi}(\zeta, \eta) = \zeta \sin \varphi - n_j \eta \cos \varphi$, with suitable choices of $\varphi \in [0, 2\pi]$, to estimate the growth of $(x_j(2k\pi), x'_j(2k\pi))$ with respect to $k \in \mathbb{Z}$. As in the proof of Theorem 2.1, if $n_j \in \mathbb{N}$, then we have that

$$V_{j,\varphi}(x_j(2\pi), x'_j(2\pi)) - V_{j,\varphi}(x_j(0), x'_j(0)) = \int_0^{2\pi} [p_j(t) - h_j(x(t))] \sin(n_j t + \varphi) dt \tag{3.1}$$

and that there exists $\varphi_j^0 \in [0, 2\pi]$ such that

$$\int_0^{2\pi} p_j(t) \sin(n_j t + \varphi_j^0) dt = \left| \int_0^{2\pi} p_j(t)e^{in_j t} dt \right|.$$

The estimate of $\int_0^{2\pi} h_j(x(t)) \sin(n_j t + \varphi) dt$ for large solutions will depend on the particular form of the nonlinear term h_j : we consider cyclic and radial dependencies. In any case, we need an estimate of the solution on $[0, 2\pi]$ with respect to initial conditions. A straightforward application of the variation of constants formula shows that

$$x_j(t) = x_j(0) \cos n_j t + \frac{x'_j(0)}{n_j} \sin n_j t + \frac{1}{n_j} \int_0^t [p_j(s) - h_j(x(s))] \sin n_j(t - s) ds$$

$j = 1, \dots, d$

if x is any solution of our system. In particular, the boundedness of h_j and p_j implies the following estimate:

$$x_j(t) = A_j \sin(n_j t + \omega_j) + \sigma_j(t)$$

$$A_j = \sqrt{x_j^2(0) + \frac{x'_j(0)^2}{n_j^2}}, \quad \omega_j \in [0, 2\pi], \quad \|\sigma_j\|_{C^2([0,2\pi])} \leq C, \tag{3.2}$$

where the constant C is independent of A_j and j .

3.1 Systems with Cyclic Coupling

Here we assume that system 2.1 is cyclically coupled, that is

$$h_j(x) = h_j(x_{j+1})$$

for each $j \in \{1, \dots, d\}$ (as usual, we use the cyclic agreement $x_{d+1} = x_1$); cf. (1.5). In particular, we have that $h_j : \mathbb{R} \rightarrow \mathbb{R}$ is locally Lipschitz continuous and bounded for each $j \in \{1, \dots, d\}$. Henceforth, we will thus write system (2.1) as

$$x_j'' + n_j^2 x_j + h_j(x_{j+1}) = p_j(t), \quad j \in \{1, \dots, d\}. \tag{3.3}$$

For this subsection, we also introduce the notations

$$\bar{h}_j(\pm\infty) = \limsup_{s \rightarrow \pm\infty} h_j(s), \quad \underline{h}_j(\pm\infty) = \liminf_{s \rightarrow \pm\infty} h_j(s),$$

and

$$\Delta h_j = \max\{\bar{h}_j(+\infty), \bar{h}_j(-\infty)\} - \min\{\underline{h}_j(+\infty), \underline{h}_j(-\infty)\}.$$

Notice that, when h_j has limits $h_j(\pm\infty)$ at infinity, then

$$\Delta h_j = |h_j(+\infty) - h_j(-\infty)|.$$

Our result reads as follows.

Theorem 3.1 *In the previous setting, assume that*

$$n_j \in \mathbb{N} \quad \text{and} \quad 2\Delta h_j < \left| \int_0^{2\pi} p_j(t) e^{in_j t} dt \right|, \quad \text{for every } j \in \{1, \dots, d\}.$$

Then, for every $j \in \{1, \dots, d\}$ there exist open sets $C_j^-, C_j^+ \subset \mathbb{R}^2$ such that $\mathbb{R}^2 \setminus (C_j^+ \cup C_j^-)$ is compact and, setting

$$C := \prod_{j=1}^d (C_j^- \cup C_j^+),$$

the following holds true:

(i) *for every solution x of (3.3),*

$$(x(0), x'(0)) \in C \implies \sup_{t \in \mathbb{R}} (x_j(t)^2 + x_j'(t)^2) = +\infty, \quad \text{for every } j \in \{1, \dots, d\}.$$

Moreover, setting

$$C^- = \prod_{j=1}^d C_j^- \quad \text{and} \quad C^+ = \prod_{j=1}^d C_j^+,$$

the following hold:

(ii) $C^- \cap C^+$ *has infinite measure;*

(iii) *for every solution x of (3.3),*

$$(x(0), x'(0)) \in C^- \implies \lim_{t \rightarrow -\infty} (x_j(t)^2 + x_j'(t)^2) = +\infty, \quad \text{for every } j \in \{1, \dots, d\},$$

$$(x(0), x'(0)) \in C^+ \implies \lim_{t \rightarrow +\infty} (x_j(t)^2 + x_j'(t)^2) = +\infty, \quad \text{for every } j \in \{1, \dots, d\}.$$

Let us explain more informally the meaning of Theorem 3.1. To this end, notice that

$$\mathcal{C}^- \cap \mathcal{C}^+ \subset \mathcal{C}^\pm \subset \mathcal{C}.$$

The set \mathcal{C} is the largest one: its projection $\mathcal{C}_j^- \cup \mathcal{C}_j^+$ on the j -th factor \mathbb{R}^2 has compact complement. The sets \mathcal{C}^\pm are smaller (and indeed it will be clear from the proof that their components \mathcal{C}_j^\pm are not the complement of a compact set) but they have the property of having infinite measure: even more, their intersection $\mathcal{C}^- \cap \mathcal{C}^+$ has infinite measure, as well. The unbounded properties of the solutions starting on this sets can be described as follows:

- (i) for vector solutions x starting on \mathcal{C} , each component x_j is unbounded in the phase-plane: it could be, however, that some component is unbounded in the past and some other in the future;
- (ii) for vector solutions x starting on \mathcal{C}^- (resp., \mathcal{C}^+), each component x_j is unbounded in the past (resp., in the future);
- (iii) for vector solutions x starting on $\mathcal{C}^- \cap \mathcal{C}^+$, each component x_j is unbounded both in the past and in the future.

Proof We fix $\Gamma > 0$ such that

$$\int_0^{2\pi} p_j(t) \sin(n_j t + \varphi_j^0) dt = \left| \int_0^{2\pi} p_j(t) e^{in_j t} dt \right| > 2(\Delta h_j + \Gamma), \quad j \in \{1, \dots, d\}.$$

By continuity, there exist open intervals I_j containing φ_j^0 such that

$$\int_0^{2\pi} p_j(t) \sin(n_j t + \varphi_j) dt > 2(\Delta h_j + \Gamma), \quad \forall \varphi_j \in I_j \text{ and } j \in \{1, \dots, d\}. \quad (3.4)$$

We claim that:

$$\begin{aligned} & \limsup_{A_{j+1} \rightarrow +\infty} \int_0^{2\pi} h_j(x_{j+1}(t)) \sin(n_j t + \varphi) dt \\ & \leq 2\Delta h_j, \quad \text{uniformly w.r.t. } \varphi \in [0, 2\pi] \text{ and } A_i, i \neq j + 1, \end{aligned} \quad (3.5)$$

where we recall that $A_{j+1} \rightarrow +\infty$ is equivalent to $\left| (x_{j+1}(0), x'_{j+1}(0)) \right| \rightarrow +\infty$, as it can be seen in (3.2). Indeed, by Fatou's lemma we have that

$$\limsup_{A_{j+1} \rightarrow +\infty} \int_0^{2\pi} h_j(x_{j+1}(t)) \sin(n_j t + \varphi) dt \leq \int_0^{2\pi} \limsup_{A_{j+1} \rightarrow +\infty} [h_j(x_{j+1}(t)) \sin(n_j t + \varphi)] dt$$

and estimate (3.2) shows that for almost every $t \in [0, \pi]$ we have that either $x_{j+i}(t) \rightarrow +\infty$ or $x_{j+i}(t) \rightarrow -\infty$ as $A_{j+1} \rightarrow +\infty$ and these limits hold uniformly w.r.t. A_i for $i \neq j + 1$. Therefore, we deduce that:

$$\begin{aligned} & \limsup_{A_{j+1} \rightarrow +\infty} [h_j(x_{j+1}(t)) \sin(n_j t + \varphi)] \\ &= \sin^+(n_j t + \varphi) \limsup_{A_{j+1} \rightarrow +\infty} h_j(x_{j+1}(t)) - \sin^-(n_j t + \varphi) \liminf_{A_{j+1} \rightarrow +\infty} h_j(x_{j+1}(t)) \\ &\leq \sin^+(n_j t + \varphi) \max\{\bar{h}_j(+\infty), \bar{h}_j(-\infty)\} - \sin^-(n_j t + \varphi) \min\{\underline{h}_j(+\infty), \underline{h}_j(-\infty)\} \end{aligned}$$

for almost every $t \in [0, 2\pi]$. Since $\int_0^{2\pi} \sin^\pm(n_j t + \varphi) dt = 2$, we obtain (3.5).

Thanks to (3.5), there is a constant $A > 0$ such that

$$x_{j+1}(0)^2 + x'_{j+1}(0)^2 \geq A^2 \implies \int_0^{2\pi} h_j(x_{j+1}(t)) \sin(n_j t + \varphi) dt \leq 2\Delta h_j + \Gamma, \quad \forall \varphi \in [0, 2\pi],$$

for each $j \in \{1, \dots, d\}$. Hence, we deduce that

$$\begin{aligned} x_{j+1}(0)^2 + x'_{j+1}(0)^2 \geq A^2 &\implies V_{j,\varphi_j}(x_j(2\pi), x'_j(2\pi)) - V_{j,\varphi_j}(x_j(0), x'_j(0)) \geq \Gamma, \\ &\forall \varphi_j \in I_j, \end{aligned}$$

by using (3.1) and (3.4).

Let us define

$$\bar{V}_j(A) = \max\{V_{j,\varphi}(\zeta, \eta) : |(\zeta, \eta)| \leq A \text{ and } \varphi \in [0, 2\pi]\}.$$

If the initial conditions satisfy $V_{j,\varphi_j}(x_j(0), x'_j(0)) > \bar{V}_j(A)$ for some $\varphi_j \in I_j$ and all $j \in \{1, \dots, d\}$, then we have that $x_j(0)^2 + x'_j(0)^2 \geq A^2$ for all $j \in \{1, \dots, d\}$ and, hence,

$$V_{j,\varphi_j}(x_j(2\pi), x'_j(2\pi)) \geq V_{j,\varphi_j}(x_j(0), x'_j(0)) + \Gamma > V_{j,\varphi_j}(x_j(0), x'_j(0)) \geq A, \quad \forall j \in \{1, \dots, d\}.$$

Therefore, we obtain recursively that

$$V_{j,\varphi_j}(x_j(2k\pi), x'_j(2k\pi)) - V_{j,\varphi_j}(x_j(0), x'_j(0)) \geq k\Gamma, \quad \forall k \in \mathbb{N} \text{ and } j \in \{1, \dots, d\},$$

which implies that $x_j(2k\pi)^2 + x'_j(2k\pi)^2 \rightarrow +\infty$ as $k \rightarrow +\infty$.

In a similar way, if the initial conditions satisfy $V_{j,\varphi_j}(x_j(0), x'_j(0)) < -\bar{V}_j(A)$ for some $\varphi_j \in I_j$ and all $j \in \{1, \dots, d\}$, then we can show that $x_j(2k\pi)^2 + x'_j(2k\pi)^2 \rightarrow +\infty$ as $k \rightarrow -\infty$.

We observe now that, for a fixed $j \in \{1, \dots, d\}$ and a fixed $\varphi_j \in I_j$, the inequalities $V_{j,\varphi_j}(\zeta, \eta) < -\bar{V}_j(A)$ and $V_{j,\varphi_j}(\zeta, \eta) > \bar{V}_j(A)$ define two opposite half-planes in \mathbb{R}^2 that originate from the two parallel straight lines $V_{j,\varphi_j}(\zeta, \eta) = \pm \bar{V}_j(A)$. For each $j \in \{1, \dots, d\}$ we fix two angles $\varphi_j^1, \varphi_j^2 \in I_j$ such that $0 < |\varphi_j^1 - \varphi_j^2| < \pi$ and define the open regions

$$\begin{aligned} \mathcal{C}_j^+ &= \{(\zeta, \eta) \in \mathbb{R}^2 : V_{j,\varphi_j^1}(\zeta, \eta) > \bar{V}_j(A)\} \cup \{(\zeta, \eta) \in \mathbb{R}^2 : V_{j,\varphi_j^2}(\zeta, \eta) > \bar{V}_j(A)\} \\ \mathcal{C}_j^- &= \{(\zeta, \eta) \in \mathbb{R}^2 : V_{j,\varphi_j^1}(\zeta, \eta) < -\bar{V}_j(A)\} \cup \{(\zeta, \eta) \in \mathbb{R}^2 : V_{j,\varphi_j^2}(\zeta, \eta) < -\bar{V}_j(A)\}, \end{aligned}$$

which are actually two reflex angles in the plane and opposite to each other with respect to the origin. In particular $\mathcal{C}_j^+ \cap \mathcal{C}_j^-$ is made up by two opposite and disjoint angles and, thus, has infinite measure, while $\mathbb{R}^2 \setminus (\mathcal{C}_j^+ \cup \mathcal{C}_j^-)$ is a compact parallelogram.

We conclude by using the argument at the beginning of the proof of Theorem 2.1. □

3.2 Systems with Radial Coupling

We assume here that the nonlinear term depends only on the Euclidean norm of the vector solution, that is

$$h_j(x) = h_j(|x|), \quad j \in \{1, \dots, d\};$$

cf. (1.6). Therefore, system (2.1) becomes

$$x_j'' + n_j^2 x_j + h_j(|x|) = p_j(t), \quad j \in \{1, \dots, d\}, \tag{3.6}$$

where $h_j : [0, +\infty) \rightarrow \mathbb{R}$ is locally Lipschitz continuous and bounded, for $j \in \{1, \dots, d\}$. In this subsection we also set

$$\begin{aligned} \bar{h}_j(+\infty) &= \limsup_{s \rightarrow +\infty} h_j(s), & \underline{h}_j(+\infty) &= \liminf_{s \rightarrow +\infty} h_j(s) \quad \text{and} \\ \Delta h_j &= \bar{h}_j(+\infty) - \underline{h}_j(+\infty), & \forall j &\in \{1, \dots, d\}. \end{aligned}$$

Our result reads as follows.

Theorem 3.2 *In the previous setting, assume that*

$$n_j \in \mathbb{N} \quad \text{and} \quad 2\Delta h_j < \left| \int_0^{2\pi} p_j(t) e^{in_j t} dt \right|, \quad \text{for some } j \in \{1, \dots, d\}.$$

Then, there exist open sets $\mathcal{C}_j^-, \mathcal{C}_j^+ \subset \mathbb{R}^2$ such that $\mathbb{R}^2 \setminus (\mathcal{C}_j^- \cup \mathcal{C}_j^+)$ is compact, $\mathcal{C}_j^- \cap \mathcal{C}_j^+$ has infinite measure and, moreover, the following holds true for every solution x of (3.6):

$$\begin{aligned} (x_j(0), x_j'(0)) \in \mathcal{C}_j^- &\implies \lim_{t \rightarrow -\infty} (x_j(t)^2 + x_j'(t)^2) = +\infty; \\ (x_j(0), x_j'(0)) \in \mathcal{C}_j^+ &\implies \lim_{t \rightarrow +\infty} (x_j(t)^2 + x_j'(t)^2) = +\infty. \end{aligned}$$

Let us notice that, contrarily to Theorem 3.1, both the assumptions and the conclusions of Theorem 3.2 refer to a component x_j of the vector solution x (from this point of view, the statement is more similar to the one of Theorem 2.1).

Proof As in the proof of Theorem 3.1, we fix $\Gamma > 0$ and an open interval $I_j \subset [0, 2\pi]$ such that

$$\int_0^{2\pi} p_j(t) \sin(n_j t + \varphi_j) dt > 2(\Delta h_j + \Gamma), \quad \forall \varphi_j \in I_j. \tag{3.7}$$

We claim that

$$\begin{aligned} \limsup_{A_j \rightarrow +\infty} \int_0^{2\pi} h_j(|x(t)|) \sin(n_j t + \varphi) dt &\leq 2\Delta h_j, \\ &\text{uniformly w.r.t. } \varphi \in [0, 2\pi] \text{ and } A_i, \text{ for } i \neq j. \end{aligned} \tag{3.8}$$

Again, by Fatou’s lemma we have that

$$\limsup_{A_j \rightarrow +\infty} \int_0^{2\pi} h_j(|x(t)|) \sin(n_j t + \varphi) dt \leq \int_0^{2\pi} \limsup_{A_j \rightarrow +\infty} [h_j(|x(t)|) \sin(n_j t + \varphi)] dt$$

and estimate (3.2) shows that for almost every $t \in [0, \pi]$ we have that $|x(t)| \geq |x_j(t)| \rightarrow +\infty$ as $A_j \rightarrow +\infty$ (still uniformly w.r.t. $A_i, i \neq j$). Therefore, we deduce that

$$\limsup_{A_j \rightarrow +\infty} [h_j(|x(t)|) \sin(n_j t + \varphi)] = \sin^+(n_j t + \varphi) \bar{h}_j(+\infty) - \sin^-(n_j t + \varphi) \underline{h}_j(+\infty)$$

for almost every $t \in [0, 2\pi]$ and we obtain (3.8).

Thanks to (3.8), there is a constant $A > 0$ such that

$$x_j(0)^2 + x'_j(0)^2 \geq A^2 \implies \int_0^{2\pi} h_j(|x(t)|) \sin(n_j t + \varphi) dt \leq 2\Delta h_j + \Gamma, \quad \forall \varphi \in [0, 2\pi].$$

Hence, we deduce that

$$x_j(0)^2 + x'_j(0)^2 \geq A^2 \implies V_{j,\varphi_j}(x_j(2\pi), x'_j(2\pi)) - V_{j,\varphi_j}(x_j(0), x'_j(0)) \geq \Gamma, \quad \forall \varphi_j \in I_j,$$

by using (3.1) and (3.7).

Let us define $\bar{V}_j(A) = \max\{V_{j,\varphi}(\zeta, \eta) : |(\zeta, \eta)| \leq A \text{ and } \varphi \in [0, 2\pi]\}$. If the initial conditions satisfy $V_{j,\varphi_j}(x_j(0), x'_j(0)) > \bar{V}_j(A)$ for some $\varphi_j \in I_j$, then we have that $x_j(0)^2 + x'_j(0)^2 \geq A^2$ and, hence,

$$V_{j,\varphi_j}(x_j(2\pi), x'_j(2\pi)) \geq V_{j,\varphi_j}(x_j(0), x'_j(0)) + \Gamma > V_{j,\varphi_j}(x_j(0), x'_j(0)) \geq A.$$

Therefore, we obtain recursively that

$$V_{j,\varphi_j}(x_j(2k\pi), x'_j(2k\pi)) - V_{j,\varphi_j}(x_j(0), x'_j(0)) \geq k\Gamma, \quad \forall k \in \mathbb{N},$$

which implies that $x_j(2k\pi)^2 + x'_j(2k\pi)^2 \rightarrow +\infty$ as $k \rightarrow +\infty$.

In a similar way, if the initial conditions satisfy $V_{j,\varphi_j}(x_j(0), x'_j(0)) < -\bar{V}_j(A)$ for some $\varphi_j \in I_j$, then we can show that $x_j(2k\pi)^2 + x'_j(2k\pi)^2 \rightarrow +\infty$ as $k \rightarrow -\infty$.

Now, we define the open regions

$$C_j^+ = \{(\zeta, \eta) \in \mathbb{R}^2 : V_{j,\varphi_j^1}(\zeta, \eta) > \bar{V}_j(A)\} \cup \{(\zeta, \eta) \in \mathbb{R}^2 : V_{j,\varphi_j^2}(\zeta, \eta) > \bar{V}_j(A)\},$$

$$C_j^- = \{(\zeta, \eta) \in \mathbb{R}^2 : V_{j,\varphi_j^1}(\zeta, \eta) < -\bar{V}_j(A)\} \cup \{(\zeta, \eta) \in \mathbb{R}^2 : V_{j,\varphi_j^2}(\zeta, \eta) < -\bar{V}_j(A)\},$$

and we conclude as in the proof of Theorem 3.1. □

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